

Q12 -- Permanent Magnetization

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12. Electricity and Magnetism (Fall 2005)

An infinitely long cylinder of radius a exhibits a permanent magnetization with its magnetization vector given by

$$\begin{aligned} \mathbf{M}(\mathbf{r}) &= \alpha r^2 \hat{\mathbf{z}} & r \leq a \\ \mathbf{M}(\mathbf{r}) &= 0 & r > a \end{aligned}$$

where α is a constant, r is the (cylindrical) radial coordinate and $\hat{\mathbf{z}}$ is a unit vector along the axis of the cylinder.

- (a) Find the magnetic vector field $\mathbf{B}$ for $r < a$ and for $r > a$.

Hint: In cylindrical coordinates

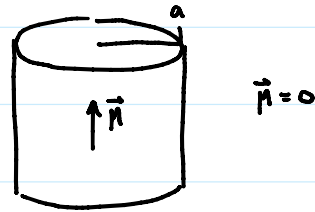
$$(\nabla \times \mathbf{F})_\phi = \frac{\partial F_z}{\partial r} - \frac{\partial F_r}{\partial z}$$

- (b) Determine the value of

$$\oint \mathbf{A} \cdot d\mathbf{l}$$

along a circular path of radius $b > a$, encircling (in the $\hat{\phi}$ direction) and concentric with the magnetized cylinder. $\mathbf{A}$ is the magnetic vector potential.

- (c) Find the force per unit volume experienced by the material at a location $r < a$.
(d) What will happen to the cylinder if α is suddenly increased to a very large value?



(a) Find $\vec{B}$:

$$\begin{aligned} \nabla \times \vec{B} &= \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} \\ \Rightarrow \vec{J} &= \vec{J}_n + \vec{J}_f \end{aligned}$$

o no free current and no time-varying electric field

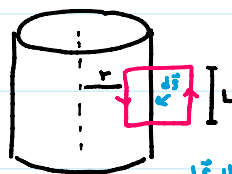
$$\nabla \times \vec{H} = \vec{J}_f = 0 \Rightarrow \vec{H} = -\nabla \psi_m \quad \text{w/} \quad \vec{B} = \mu_0 [\vec{M} + \vec{H}]$$

o only contribution to $\vec{B}$ is from permanent $\vec{M}$

Method 1: $\vec{B}$ from currents

$$\begin{aligned} \vec{J}_n &= \nabla \times \vec{M} \\ &= \nabla \times (\alpha r^2 \hat{\mathbf{z}}) \\ &= -\frac{\partial}{\partial r} (\alpha r^2) \hat{\phi} \\ &= -2\alpha r \hat{\phi} \end{aligned} \quad \begin{aligned} \vec{K}_n &= \vec{M} \times \hat{n} \big|_{r=a} \\ &= [(\alpha r^2 \hat{\mathbf{z}}) \times \hat{\mathbf{r}}]_{r=a} \\ &= \alpha a^2 (\hat{\mathbf{z}} \times \hat{\mathbf{r}}) \\ &= \alpha a^2 \hat{\phi} \end{aligned}$$

Notice that we have a solenoidal field by RHR, thus $\vec{B}_{out} = 0$



$$d\vec{s} \parallel \hat{\phi}$$

$$\begin{aligned} \nabla \times \vec{B} &= \mu_0 \vec{J} \\ \vec{B} &\parallel \hat{\mathbf{z}} \end{aligned}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$B_z(-L) = \mu_0 I_{enc} = \mu_0 \left\{ \int \vec{J} \cdot d\vec{s} \right\}$$

$$= \mu_0 \left\{ \int \vec{K}_n(\phi) \cdot d\vec{s} + \int \vec{J} \cdot d\vec{s} \right\}$$

$$= \mu_0 \left\{ \int \vec{K} \cdot d\vec{l}_1 + \int \vec{J} \cdot d\vec{s} \right\}$$

$$= \mu_0 K L (\hat{\phi} \cdot \hat{\phi}) + \mu_0 (2\alpha) \int_{-L}^L r dr dz (-\hat{\phi} \cdot -\hat{\phi})$$

Method 1

$$= \mu_0 \int \mathbf{J} \cdot d\mathbf{A} = \mu_0 \int \mathbf{J} \cdot \mathbf{e}_z dA$$

$$= \mu_0 K L (\hat{\phi} - \hat{\phi}) + \mu_0 (2\alpha) \int_0^a r dr dz (-\hat{\phi} - \hat{\phi})$$

$$= -\mu_0 \alpha a^2 L + \mu_0 \alpha (a^2 - r^2) L$$

$$= -\mu_0 \alpha r^2 L$$

$$\vec{B} = \begin{cases} \mu_0 \alpha r^2 \hat{z} & r \leq a \\ 0 & r > a \end{cases}$$

Method 2: Since $\vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M} = 0$, Ampere's Law $\vec{\nabla} \times \vec{H} = \vec{J} = 0$ uniquely defines

the field. $\vec{H}$ could be constant, but $\oint \vec{H} \cdot d\vec{\ell} = -HL = 0$

$$\{\vec{H} = 0\}$$

$$\text{thus } \vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M} = 0$$

$$\vec{B} = \mu_0 \vec{H} \text{ everywhere}$$

$$\vec{B} = \begin{cases} \mu_0 \alpha r^2 \hat{z} & r \leq a \\ 0 & r > a \end{cases}$$

Method 3: Using Fictitious Magnetic Charge (see Zangwill 415 for review)

$$(1) \vec{\nabla} \cdot \vec{B} = \mu_0 \vec{\nabla} \cdot [\vec{M} + \vec{H}] = 0$$

$$\therefore \vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M} = \rho^* \text{ (by analogy } \vec{\nabla} \cdot \vec{E} = \rho/\epsilon_0)$$

$$\Rightarrow \vec{\nabla}^2 \psi_m = -\rho^*$$

$$\text{However } \vec{\nabla} \cdot \vec{M} = \frac{\partial}{\partial z} (\alpha r^2) = 0 \text{ s.t. } \rho^* = 0 \text{ \& } \vec{\nabla} \cdot \vec{H} = 0$$

$$(2) \text{ The M.C. } \hat{n} \cdot (\vec{B}_2 - \vec{B}_1) = 0 \Rightarrow \hat{n} \cdot \mu_0 [\vec{H}_2 + \vec{M}_2 - (\vec{H}_1 + \vec{M}_1)] = 0$$

$$\hat{n} \cdot [\vec{H}_2 - \vec{H}_1]_s = -\hat{n} \cdot [\vec{M}_2 - \vec{M}_1]_s \quad \begin{matrix} \vec{H}_2 \\ \vec{H}_1 \end{matrix} \nearrow \hat{n}_i$$

$$\therefore \hat{n}_i \cdot [\vec{H}_2 - \vec{H}_1]_s = -\hat{n}_i \cdot [\vec{M}_2 - \vec{M}_1]_s = \sigma^* = 0 \text{ (by analogy } \hat{n} \cdot [\vec{E}_2 - \vec{E}_1]_s = \sigma/\epsilon_0)$$

$$H_2^\perp = H_1^\perp \big|_s \text{ (perp to surface)}$$

$$(3) \hat{n}_i \times [\vec{H}_2 - \vec{H}_1] = \vec{J}_f = 0$$

$$H_2^\parallel = H_1^\parallel \big|_s$$

$$\text{Thus, } H_2^\parallel = H_1^\parallel \big|_s, H_2^\perp = H_1^\perp \big|_s, \vec{\nabla} \cdot \vec{H} = \rho^* = 0, \text{ and } \vec{\nabla} \times \vec{H} = \vec{J}_f = 0$$

Thus, $H_z'' = H_z''|_s$, $H_z^\perp = H_z^\perp|_s$, $\vec{\nabla} \cdot \vec{H} = \rho^* = 0$, and $\vec{\nabla} \times \vec{H} = \vec{J}_s = 0$

imply that $\vec{H} = 0$ everywhere

$$\therefore \boxed{\vec{B} = \mu_0 \vec{H}}$$

(b) Determine $\int_C \vec{A} \cdot d\vec{\ell}$ for $b > a$, C follows $\hat{\phi}$, concentric

Notice that $\int (\vec{\nabla} \times \vec{B}) \cdot d\vec{s} = \oint \vec{B} \cdot d\vec{\ell}$ (form we want)

then $\int (\vec{\nabla} \times \vec{A}) \cdot d\vec{s} = \oint \vec{A} \cdot d\vec{\ell} = \int \vec{B} \cdot d\vec{s} = \Phi_B$

$$\begin{aligned} \oint \vec{A} \cdot d\vec{\ell} &= \int_0^b \mu_0 \vec{M} \cdot d\vec{s} = \mu_0 \int_0^a \alpha r^2 \hat{z} \cdot \hat{z} r dr d\phi + 0 \\ &= \boxed{\frac{\mu_0 \pi \alpha a^4}{2}} \end{aligned}$$

(c) find f (force/vol) @ $r < a$ on material

$$\vec{F} = \int d^3r \vec{J} \times \vec{B}$$

$$\vec{f} = \vec{J} \times \vec{B} = \mu_0 \vec{J} \times \vec{M} = (\vec{\nabla} \times \vec{B}) \times \vec{M}$$

$$= -\vec{M} \times (\vec{\nabla} \times \vec{B}) = -[\vec{\nabla}(\vec{M} \cdot \vec{B}) - \vec{B}(\vec{\nabla} \cdot \vec{M})]$$

$$= -\vec{\nabla}(\vec{M} \cdot \vec{B}) = -\mu_0 \vec{\nabla}(\vec{M}^2)$$

$$\boxed{\vec{f} = -\mu_0 \vec{\nabla}(\alpha^2 r^4) = -4\mu_0 \alpha^2 r^3 \hat{r} \quad (r < a)}$$

cyl $\hat{r}$

(d) limit $\alpha \rightarrow \infty$, $\vec{f} \rightarrow -\infty$ therefore

the cylinder will collapse into a thin wire
as it compresses on itself